

2A Single Input I ²C, Standalone Switch-Mode Li-Ion Battery Charger with Power-Path Management

Check for Samples: [bq24250](http://www.ti.com/product/bq24250#samples), [bq24251,](http://www.ti.com/product/bq24251#samples) [bq24253](http://www.ti.com/product/bq24253#samples)

¹FEATURES

- **²³• High-efficiency Switch-mode Charger with • Complete System Level Protection Separate Power Path – Input UVLO, Input Over-voltage Protection**
- **Missing Battery – Input Current Limit**
- **• USB Charging Compliant – Charge Current Limit**
	- **– Selectable Input Current Limit of 100 mA, – Thermal Regulation ⁵⁰⁰ mA, ⁹⁰⁰ mA, 1.5 A, and ² ^A – Thermal Shutdown**
- **• BC1.2 Compatible D+, D– Detection**
- **• In Host Mode (after I ²C communication starts Monitoring Input and before watchdog timer times out)**
	- **– Programmable Battery Charge Voltage, • ²⁰ ^V Maximum Input Voltage Rating**
	- $-$ **Programmable Charge Current (I_{CHG})**
	-
	- **– Programmable Input Current Limit (ILIM) ^A Charging Rate – Programmable Input Voltage Based • Open Drain Status Outputs Dynamic Power Management threshold,**
	- **– Programmable Input Overvoltage • AnyBoot Robust Battery Detection Algorithm**
 • AnyBoot Robust Battery Detection Algorithm
 • Charge Time Optimizer for improved charge
	-
- **• Resistor Programmable Defaults for:**
	- **– ICHG up to 2 A with Current Monitoring Output (ISET) APPLICATIONS**
	- **– ILIM up to 2 A with Current Monitoring**
	- **– VIN_DPM (VDPM)**
- **• Watchdog Timer Disable Bit**
- **• Integrated 4.9 V, 50 mA LDO**

DESCRIPTION

-
- **• Start up System from Deeply Discharged or (OVP), Battery OVP, Sleep Mode, VIN_DPM**
	-
	-
	-
	-
	- **– Voltage Based, JEITA Compatible NTC**
	- **– Safety Timer**
	-
	- **^VBATREG • 10.5 ^V Maximum Operating Input Voltage**
	- **• Low RDS(on) Integrated Power FETs for up to 2**
	-
	- **• Synchronous Fixed-frequency PWM Controller (VIN_DPM) Operating at 3MHz for Small Inductor Support**
		-
- **• Charge Time Optimizer for improved charge – Programmable Safety Timer times at any given charge current**
	- **• 2.4 x 2.0 mm 30-ball WCSP Package**

- **Mobile Phones and Smart Phones**
- **• MP3 Players**
- **• Portable Media Players**
- **• Handheld Devices**

The bq24250, 1, 3 is a highly integrated single-cell Li-Ion battery charger and system power-path management device targeted for space-limited, portable applications with high capacity batteries. The single cell charger has a single input that operates from either a USB port or AC wall adapter for a versatile solution.

The power path management feature allows the bq24250, 1, 3 to power the system from a high efficiency DC/DC converter while simultaneously and independently charging the battery. The charger monitors the battery current at all times and reduces the charge current when the system load requires current above the input current limit. This allows for proper charge termination and enables the system to run with a defective or absent battery pack. Additionally, this enables instant system turn-on even with a totally discharged battery or no battery. The powerpath management architecture also permits the battery to supplement the system current requirements when the adapter cannot deliver the peak system currents. This enables the use of a smaller adapter.

AA

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These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

DESCRIPTION (CONTINUED)

The battery is charged in four phases: trickle charge, pre-charge, constant current and constant voltage. In all charge phases, an internal control loop monitors the IC junction temperature and reduces the charge current if the internal temperature threshold is exceeded. Additionally, a voltage-based, JEITA compatible battery pack thermistor monitoring input (TS) is included that monitors battery temperature for safe charging.

Typical Application

AVAILABLE OPTIONS

ORDERING INFORMATION(1)(2)

(1) This product is RoHS compatible, including a lead concentration that does not exceed 0.1% of total product weight, and is suitable for use in specified lead-free soldering processes. In addition, this product uses package materials that do not contain halogens, including bromine (Br) or antimony (Sb) above 0.1% of total product weight.

(2) For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI website at www.ti.com.

(3) Preview

ABSOLUTE MAXIMUM RATINGS(1)

over operating free-air temperature range (unless otherwise noted)

(1) Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) The human body model is a 100-pF capacitor discharged through a 1.5-kΩ resistor into each pin.

RECOMMENDED OPERATING CONDITIONS

All voltages are with respect to PGND if not specified. Currents are positive into, negative out of the specified terminal. Consult Packaging Section of the data book for thermal limitations and considerations of packages

(1) The inherent switching noise voltage spikes should not exceed the absolute maximum rating on either the BOOT or SW pins. Small routing loops for the power nets in layout minimize switching noise.

THERMAL INFORMATION

(1) For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report, [SPRA953](http://www.ti.com/lit/pdf/spra953).

ELECTRICAL CHARACTERISTICS

 V_{UVLO} < V_{IN} < V_{OVP} and V_{IN} > V_{BAT} + V_{SLP} , T_J = 0°C-125°C and T_J = 25°C for typical values (unless otherwise noted)

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ELECTRICAL CHARACTERISTICS (continued)

 V_{UVLO} < V_{IN} < V_{OVP} and V_{IN} > V_{BAT} + V_{SLP} , T_J = 0°C-125°C and T_J = 25°C for typical values (unless otherwise noted)

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ELECTRICAL CHARACTERISTICS (continued)

 V_{UVLO} < V_{IN} < V_{OVP} and V_{IN} > V_{BAT} + V_{SLP} , T_J = 0°C-125°C and T_J = 25°C for typical values (unless otherwise noted)

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ELECTRICAL CHARACTERISTICS (continued)

 V_{UVLO} < V_{IN} < V_{OVP} and V_{IN} > V_{BAT} + V_{SLP} , T_J = 0°C-125°C and T_J = 25°C for typical values (unless otherwise noted)

BLOCK DIAGRAM

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PIN DESCRIPTIONS (continued)

TYPICAL APPLICATION CIRCUITS

Figure 1. bq24250 Typical Application Circuit

TYPICAL CHARACTERISTICS

Figure 4.

Figure 5.

TYPICAL CHARACTERISTICS (continued)

TYPICAL CHARACTERISTICS (continued)

TYPICAL CHARACTERISTICS (continued)

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CHARGE PROFILE

The bq2425x family provides a switch-mode buck regulator with output power path and a charge controller to provide optimum performance over the full battery charge cycle. The control loop for the buck regulator has 7 primary feedback loops that can set the duty cycle:

- 1. Constant Current (CC)
- 2. Constant Voltage (CV)
- 3. Minimum System Voltage (MINSYS)
- 4. Input Current (I_{ILIM})
- 5. Input Voltage $(V_{IN)PPM}$
- 6. Die Temperature
- 7. Cycle by Cycle Current

The feedback with the minimum duty cycle will be chosen as the active loop. The bq24250, 1, 3 support a precision Li-Ion or Li-Polymer charging system for single-cell applications. The Dynamic Power Path Management (DPPM) feature regulates the system voltage to a minimum of V_{MINSYS}, so that startup is enabled even with a missing or deeply discharged battery. This provides a much better overall user experience in mobile applications. The figure below illustrates a typical charge profile while also demonstrating the minimum system output voltage regulation.

[Figure](#page-20-0) 20 demonstrates a measured charge profile with the bq2425X while charging a 2700mAh Li-Ion battery at a charge rate of 1A.

Figure 20. bq24250 Charge Profile while Charging a 2700 mAh Battery at a 1A Charge Rate

[Figure](#page-20-1) 21 illustrates the precharge behavior of the above charge profile by narrowing the time axis to $0 - 120$ seconds.

Figure 21. bq24250 Charge Profile While Charging a 2700-mAh Battery at a 1A Charge During Precharge

EN1/EN2 PINS

The bq24250 is I²C and Stand Alone part. The EN1 and EN2 pins are available in this IC spin to support USB 2.0 compliance. These pins are used for Input Current Limit Configuration I. Set EN1 and EN2 to control the maximum input current and enable USB compliance. See [Table](#page-21-0) 1 below for programming details.

The bq24251 is also an I²C and Stand Alone part. The EN1 and EN2 are not available for this spin but the D+/Dare available to support the BC1.2 D+/D- Based Adapter Detection. It detects DCP, SDP, and CDP. Also it complies with the unconnected dead battery provision clause. D+ and D- pins are connected to the D+ and Doutputs of the USB port at power up. Also includes the detection of Apple™ and TomTom™ adapters where a 500mA input current limit is enabled. The /PG pin will remain high impedance state until the detection is completed.

The bq24253 is only Stand Alone part. Both of the D+/D- and EN1/EN2 are available for this spin. During power up, the device checks first for the D+/D-. The EN1 and EN2 do not take effect until D+/D- detection routine is over and a change on the status of the EN1 and EN2 occurred.

When the input current limit pins change state, the $V_{\text{IN-DPM}}$ threshold changes as well. See [Table](#page-21-0) 1 for the detailed truth table:

Table 1. EN1, and EN2 Truth Table(1)

(1) USB3.0 support available. Contact your local TI representative for details.

I ²C Operation (Host Mode / Default Mode)

There are two primary modes of operation when interacting with the charge parameters of the bq24250 and bq24251 chargers: 1) Host mode operation where the I²C registers set the charge parameters, and 2) Default mode where the register defaults set the charge parameters.

[Figure](#page-22-0) 22 illustrates the behavior of the bq24250 when transitioning between host mode and stand alone mode:

Figure 22. Host Mode and Stand Alone Mode Handoff

Once the battery or input is inserted and above the good thresholds, the device determines if an I²C command has been received in order to discern whether to operate from the I²C registers or the internal register defaults. In stand-alone mode the input current limit is set by the EN1/EN2 pins. If the watch dog timer is enabled, the device will enter stand alone operation once the watchdog timer expires and re-initiate the default charge settings.

External Settings: ISET, ILIM and VIN_DPM

If the external resistor settings are used, the following equations can be followed to configure the charge settings.

The fast charge current resistor (R_{ISET}) can be set by using the following formula:

$$
R_{\text{ISET}} = \frac{K_{\text{ISET}}}{I_{\text{FC}}} = \frac{250}{I_{\text{FC}}} \tag{1}
$$

Where I_{FC} is the desired fast charge current setting in Amperes.

The input current limit resistor (R_{ILIM}) can be set by using the following formula:

$$
R_{ILIM} = \frac{K_{ILIM}}{I_{IC}} = \frac{270}{I_{IC}}
$$
\n(e) is the desired input current limit in Amperes.\nd on the application diagram reference designators, the resistor R1 and R2 can be calculated as follows to\n
$$
I_{IN_DPM}
$$
\n
$$
V_{IN_DPM} = V_{DEF_PDM} \times \frac{R_1 + R_2}{I_{IC}} = 1.2 \times \frac{R_1 + R_2}{I_{IC}}
$$
\n(2)

Where I_{IC} is the desired input current limit in Amperes.

Based on the application diagram reference designators, the resistor R1 and R2 can be calculated as follows to set V_{IN_DPM} :

$$
V_{IN_DPM} = V_{REF_DPM} \times \frac{R_1 + R_2}{R_2} = 1.2V \times \frac{R_1 + R_2}{R_2}
$$

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 $\rm V_{IN_DPM}$ should be chosen first along with $\rm R_1.$ Choosing $\rm R_1$ first will ensure that $\rm R_2$ will be greater than the resistance chosen. This is the case since $V_{IN\text{ DPM}}$ should be chosen to be greater than 2x $V_{REF\text{ DPM}}$.

If external resistors are not desired in order to reduce the BOM count, the VDPM and the ILIM pins can be shorted to set the internal defaults. The ISET resistor must be floated in order to avoid an internal fault detection. Note that floating the ILIM pin will result in zero charge current if the external ISET is configured via the I^2C register. [Table](#page-23-0) 2 summarizes the settings when the ILIM, ISET, and $V_{\text{IN-DPM}}$ pins are shorted to GND:

Table 2. ILIM, VDPM, and ISET Short Behaviors

BC1.2 D+/D– Detection

The bq24251 and the bq24253 include a fully BC1.2 compatible D+/D– source detection. This detection supports the following types of ports:

- DCP (dedicated charge port)
- CDP (charging downstream port)
- SDP (standard downstream port)
- Apple™/TomTom™ ports

This D+/D– detection algorithm does not support ACA (accessory charge adapter) identification, but the input current will default to 500mA when a charge port is attached to the ACA and bq24251/3 is connected to the OTG port.

The D+/D– detection algorithm is only active when the device is in standalone mode (e.g. the host is not communicating with the device and the watch dog timer has expired). However, when the device is in host mode (e.g. host is communicating via I ²C to the device) writing a '1' to register 0x04 bit location 4 (DPDM_EN) forces the device to perform a D+/D– detection on the next power port insertion. This allows the D+/D– detection to be enabled in both host mode and default mode.

As described previously, the bq24253 is only a Stand Alone part. Both of the D+/D- and EN1/EN2 are available for this spin. The below flow diagram illustrates the behavior of the bq24253 in D+/D- detection and the effect of the EN1/EN2. During power up, the device checks first for the D+/D-. The EN1 and EN2 do not take effect until D+/D- detection routine is over and a change on the status of the EN1 and EN2 occurred.

Figure 23. bq24253 D+/D- and EN1/EN2

The D+/D– detection algorithm has 5 primary states. These states are termed the following:

- 1. Data Contact Detect
- 2. Primary Detection
- 3. Secondary Detection
- 4. Non-standard Adapter Detection (for Apple™ / TomTom™)
- 5. Detection Configuration

The DCD state determines if the device has properly connected to the D+/D– lines. If the device is not in host mode and VBUS is inserted (or DPDM_EN is true) the device enters the DCD state and enable the appropriate algorithm. If the DCD timer expires, the device enters the Non-standard Adapter Detection (for Apple™ / TomTom™) state. Otherwise it enters the Primary Detection state.

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When entering the Primary Detection state, the appropriate algorithm is enabled to determine whether to enter the secondary detection state for DCP and CDP or the secondary detection state for SDP/Non-Standard adaptors.

The non-standard adapter detection state for Apple™ / TomTom™ tests for the unique conditions for these nonstandard adapters. If the algorithm passes the unique conditions found with these adapters, it proceeds to the Detection Configuration state. Otherwise it reverts back to the primary detection state.

The secondary detection state determines whether the input port is a DCP, CDP, SDP, or other non-standard adapters. If the Primary Detection state indicated that the input port is either a DCP or CDP, the device enables the appropriate algorithm to differentiate between the two. If the Primary Detection state indicated that the input port is either a SDP or non-standard adapter, the device enables the appropriate algorithm to differentiate between these two ports. Once complete, the device continues to the Detection Configuration state.

Figure 24. Detection Configuration State

The detection configuration state sets the input current limit of the device along with the charge timer. The exception to the CDP and the SDP settings are due to the Dead Battery Provision (DBP) clause for unconnected devices. This clause states that the device can pull a maximum of 100mA when not connected due to a dead battery. During the battery wakeup time, the device sources a voltage on the D+ pin in order to comply with the DBP clause. Once the battery is good, the system can clear the D+ pin voltage by writing a '1' to address 0x07 bit position 4 (CLR_VDP). The device must connect to the host within 1sec of clearing the D+ pin voltage per the DPB clause.

A summary of the input current limits and timer configurations for each charge port type are found in [Table](#page-25-0) 3.

Transient Response

The BQ24250/1/3 includes an advanced hybrid switch mode control architecture. When the device is regulating the charge current (fast-charge), a traditional voltage mode control loop is used with a Type-3 compensation network. However, the BQ24250/1/3 switches to a current mode control loop when the device enters voltage regulation. Voltage regulation occurs in three charging conditions: 1) Minimum system voltage regulation (battery below MINSYS), 2) Battery voltage regulation (I_{BAT} < I_{CHG}), and 3) Charge Done ($V_{SYS} = V_{BAT} + 3.5\%$). This architecture allows for superior transient performance when regulating the voltage due to the simplification of the compensation when using current mode control. The below transient response plot illustrates a 0A to 2A load step with 4.7ms full cycle and 12% duty cycle. A 3.9V Li-Ion battery is used. The input voltage is set to 5V, charge current is set to 0.5A and the input current is limited to 0.5A. Note that a high line impedance input supply was used to indicate a realistic input scenario (adapter and cable). This is illustrated by the change in V_{IN} seen at the input of the IC.

[Figure](#page-26-0) 25 shows a ringing at both the input voltage and the input current. This is caused by the input current limit speed up comparator.

Figure 25. 2A Load Step Transient

AnyBoot Battery Detection

The bq2425x family includes a sophisticated battery detection algorithm used to provide the system with the proper status of the battery connection. The AnyBoot battery algorithm also guarantees the detection of voltage based battery protectors that may have a long closure time (due to the hysteresis of the protection switch and the cell capacity). The AnyBoot battery detection algorithm utilizes a dual-voltage based detection methodology where the system rail switches between two primary voltage levels. The period of the voltage level shift is 64ms and therefore the power supply rejection of the down-system electronics detects this shift as essentially DC.

The AnyBoot algorithm has essentially 3 states. The 1st state is used to determine if the device has terminated with a battery attached. If it has terminated due to the battery not being present, then the algorithm moves to the 2nd and 3rd states. The 2nd and 3rd states shift the system voltage level between 4.2V and 3.72V. In each state there are comparator checks to determine if a battery has been inserted. The two states guarantees the detection of a battery even if the voltage of the cell is at the same level of the comparator thresholds. The algorithm will remain in states 2 and 3 until a battery has been inserted. The flow diagram details for the Anyboot algorithm are shown in [Figure](#page-27-0) 26.

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Input Voltage Based DPM

During normal charging process, if the input power source is not able to support the programmed or default charging current, the supply voltage deceases. Once the supply drops to VIN_DPM, the input current limit is reduced down to prevent the further drop of the supply. When the IC enters this mode, the charge current is lower than the set. This feature ensures IC compatibility with adapters with different current capabilities without a hardware change.

Sleep Mode

The bq2425x enters the low-power sleep mode if the voltage on VIN falls below sleep-mode entry threshold, VBAT+VSLP, and VIN is higher than the under-voltage lockout threshold, VUVLO. This feature prevents draining the battery during the absence of VIN. When VIN < VBAT+VSLP, the bq2425x turns off the PWM converter, turns on the battery FET, sends a single 256µs pulse is sent on the STAT and INT outputs and the FAULT/STAT bits of the status registers are updated in the I²C. Once VIN > VBAT+VSLP with the hysteresis, the FAULT bits are cleared and the device initiates a new charge cycle.

Input Over-Voltage Protection

The bq2425x provides over-voltage protection on the input that protects downstream circuitry. The built-in input over-voltage protection to protect the device and other components against damage from overvoltage on the input supply (Voltage from VIN to PGND). When VIN > VOVP, the bq2425x turns off the PWM converter, turns the battery FET, sends a single 256μs pulse is sent on the STAT and INT outputs and the FAULT/STAT bits of the status registers and the battery/supply status registers are updated in the I²C. Once the OVP fault is removed, the FAULT bits are cleared and the device returns to normal operation. The OVP threshold for the bq24250 is programmable from 6.5V to 10.5V using VOVP bits in register #7.

NTC Monitor

The bq24250/1/3 includes the integration of an NTC monitor pin that complies with the JEITA specification (PSE also available upon request). The voltage based NTC monitor allows for the use of any NTC resistor with the use of the circuit shown in [Figure](#page-28-0) 27.

Figure 27. Voltage Based NTC circuit

The use of R3 is only necessary when the NTC does not have a beta near 3500K. When deviating from this beta, error will be introduced in the actual temperature trip thresholds. The trip thresholds are summarized below which are typical values provided in the specification table.

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RUMENTS

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When sizing for R2 and R3, it is best to solve two simultaneous equations that ensure the temperature profile of the NTC network will cross the V_{HOT} and V_{COLD} thresholds. The accuracy of the V_{WARM} and V_{COOL} thresholds will depend on the beta of the chosen NTC resistor. The two simultaneous equations are shown below:

$$
\%V_{\text{COLD}} = \frac{\left(\frac{R_3 \cdot R_{\text{NIC}}|_{\text{TCOLD}}}{R_3 + R_{\text{NIC}}|_{\text{TCOLD}}}\right)}{\left(\frac{R_3 \cdot R_{\text{NIC}}|_{\text{TCOLD}}}{R_3 + R_{\text{NIC}}|_{\text{TCOLD}}}\right) + R2} \times 100
$$
\n
$$
\%V_{\text{HOT}} = \frac{\left(\frac{R_3 \cdot R_{\text{NIC}}|_{\text{THOT}}}{R_3 + R_{\text{NIC}}|_{\text{THOT}}}\right)}{\left(\frac{R_3 \cdot R_{\text{NIC}}|_{\text{THOT}}}{R_3 + R_{\text{NIC}}|_{\text{THOT}}}\right) + R2} \times 100
$$

Where the NTC resistance at the V_{HOT} and V_{COLD} temperatures must be resolved as follows:

$$
R_{NTC}|_{TCOLD} = R_0 e^{\beta(\gamma_{TCOLD} - \gamma_{T0})}
$$

\n
$$
R_{NTC}|_{THOT} = R_0 e^{\beta(\gamma_{THOT} - \gamma_{T0})}
$$
\n(5)

To be JEITA compliant, T_{COLD} must be 0°C and T_{HOT} must be 60°C. If an NTC resistor is chosen such that the beta is 4000K and the nominal resistance is 10kΩ, the following R2 and R3 values result from the above equations:

 $R_2 = 5$ kΩ R_3 = 9.82 kΩ

[Figure](#page-29-0) 28 illustrates the temperature profile of the NTC network with R2 and R3 set to the above values.

Figure 28. Voltage Based NTC Circuit Temperature Profile

For JEITA compliance, the T_{COOL} and T_{WARM} levels are to be 10°C and 45°C respectively. However, there is some error due to the variation in beta from 3500K. As shown above, the actual temperature points at which the NTC network crosses the V_{COOL} and V_{WARM} are 13°C and 47°C respectively. This error is small but should be considered when choosing the final NTC resistor.

Once the resistors are configured, the internal JEITA algorithm will apply the below profile at each trip point for battery voltage regulation and charge current regulation.

Figure 29. JEITA Profile for Voltage and Current Regulation Loops

Dynamic Power Path Management

The bq24250/1/3 features a SYS output that powers the external system load connected to the battery. This output is active whenever a valid source is connected to IN or BAT. The following discusses the behavior of SYS with a source connected to the supply or a battery source only.

When a valid input source is connected to the input and the charge is enabled, the charge cycle is initiated. In case of VBAT > ~3.5V, the SYS output is connected to VBAT. If the SYS voltage falls to VMINSYS, it is regulated to the VSYSREG threshold to maintain the system output even with a deeply discharged or absent battery. In this mode, the SYS output voltage is regulated by the buck converter and the battery FET is linearly regulated to regulate the charge current into the battery. The current from the supply is shared between charging the battery and powering the system load at SYS.

The dynamic power path management (DPPM) circuitry of the bq24250/1/3 monitors the current limits continuously and if the SYS voltage falls to the VMINSYS voltage, it adjusts charge current to maintain the minimum system voltage and supply the load on SYS. If the charge current is reduced to zero and the load increases further, the bq24250/1/3 enters battery supplement mode. During supplement mode, the battery FET is turned on and the battery supplements the system load.

If the battery is ever 5% above the regulation threshold, the battery OVP circuit shuts the PWM converter off and the battery FET is turned on to discharge the battery to safe operating levels. Battery OVP FAULT is shown in the I2C FAULT registers.

When no input source is available at the input and the battery is connected, the battery FET is turned on similar to supplement mode. The battery must be above VBATUVLO threshold to turn on the SYS output. In this mode, the current is not regulated; however, there is a short circuit current limit. If the short circuit limit is reached, the battery FET is turned off for the deglitch time. After the deglitch time, the battery FET is turned on to test and see if the short has been removed. If it has not, the FET turns off and the process repeats until the short is removed. This process is to protect the internal FET from over current.

Production Test Mode

To aid in end mobile device product manufacturing, the bq2425x includes a Production Test Mode (PTM), where the device is essentially a DC-DC buck converter. In this mode the input current limit to the charger is disabled and the output current limit is limited only by the inductor cycle-by-cycle current (e.g. 3.5A). The PTM mode can be used to test systems with high transient loads such as GSM transmission without the need of a battery being present.

As a means of safety, the Anyboot algorithm will determine if a battery is not present at the output prior to enabling the PTM mode. If a battery is present and the software attempts to enter PTM mode, the device will not enable PTM mode.

Safety Timer

At the beginning of charging process, the bq24250/1/3 starts the safety timer. This timer is active during the entire charging process. If charging has not terminated before the safety timer expires, the IC enters suspend mode where charging is disabled. The safety timer time is selectable using the I²C interface. A single 256μs pulse is sent on the STAT and INT outputs and the FAULT/ bits of the status registers are updated in the I²C. This function prevents continuous charging of a defective battery if the host fails to reset the safety timer. The safety timer runs at 2x the normal rate under the following conditions: Pre-charge or linear mode (minimum system voltage mode), during thermal regulation where the charge current is reduced, during TS fault where the charge current reduced due to temperature rise on the battery, input current limit. The safety timer is suspended during OVP, TS fault where charge is disabled, thermal shut down, and sleep mode.

Watchdog Timer

In addition to the safety timer, the bq24250/1 contains a 50-second watchdog timer that monitors the host through the I2C interface. Once a write is performed on the I2C interface, a watchdog timer is reset and started. The watchdog timer can be disabled by writing "0" on WD_EN bit of register #1. Writing "1" on that bit enables it and reset the timer.

If the watchdog timer expires, the IC enters DEFAULT mode where the default charge parameters are loaded and charging continues. The I2C may be accessed again to re-initialize the desired values and restart the watchdog timer as long as the safety timer has not expired. Once the safety timer expires, charging is disabled.

Thermal Regulation and Thermal Shutdown

During the charging process, to prevent overheat of the chip, bq24250/1/3 monitors the junction temperature, T_J, of the die and begins to taper down the charge current once ${\sf T}_{\sf J}$ reaches the thermal regulation threshold, TREG. The charge current is reduced when the junction temperature increases above TREG. Once the charge current is reduced, the system current is reduced while the battery supplements the load to supply the system. This may cause a thermal shutdown of the IC if the die temperature rises too. At any state, if T_J exceeds TSHTDWN, bq2425x suspends charging and disables the buck converter. During thermal shutdown mode, PWM is turned off, all safety timers are suspended, and a single 256μs pulse is sent on the STAT and INT outputs and the FAULT/STAT bits of the status registers are updated in the I2C. A new charging cycle begins when T_J falls below TSHTDWN by approximately 10°C.

Fault Modes

The bq2425x family includes several hardware fault detections. This allows for specific conditions that could cause a safety concern to be detected. With this feature, the host can be alleviated from monitoring unsafe charging conditions and also allows for a "fail-safe" if the host is not present. The table below summarizes the faults that are detected and the resulting behavior.

Register Mapping and Description

Register #1

Memory location: 00, Reset state: x0xx xxxx

• **WD_FAULT –** '0' indicates no watch dog fault has occurred, where a '1' indicates a fault has previously occurred.

- **WD_EN –** Enables or disables the internal watch dog timer. A '1' enables the watch dog timer and a '0' disables it.
- **STAT** Indicates the charge controller status.
- **FAULT –** Indicates the faults that have occurred. If multiple faults occurred, they can be read by sequentially addressing this register (e.g. reading the register 2 or more times). Once all faults have been read and the device is in a non-fault state, the fault register will show "Normal". Regarding the "Input Fault & LDO Low" the IC indicates this if LDO is low and at the same time the input is below UVLO or coming out of UVLO with LDO still low.

Register #2

Memory location: 01, Reset state: 1010 1100

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- **I_{IN LIMIT}** Sets the input current limit level. When in host mode this register sets the regulation level. However, when in standalone mode (e.g. no I²C writes have occurred after power up or the WD timer has expired) the external resistor setting for I_{ILIM} sets the regulation level.
- **EN_STAT –** Enables and disables the STAT pin. When set to a '1' the STAT pin is enabled and function normally. When set to a '0' the STAT pin is disabled and the open drain FET is in HiZ mode.
- **EN TERM** Enables and disables the termination function in the charge controller. When set to a '1' the termination function will be enabled. When set to a '0' the termination function will be disabled. When termination is disabled, there are no indications of the charger terminating (i.e. STAT pin or STAT registers).
- **CE –** The charge enable bit which enables or disables the charge function. When set to a '0', the charger operates normally. When set to a '1', the charger is disables by turning off the BAT FET between SYS and BAT. The SYS pin continues to stay active via the switch mode controller if an input is present.
- **HZ_MODE** Sets the charger IC into low power standby mode. When set to a '1', the switch mode controller is disabled but the BAT FET remains ON to keep the system powered. When set to a '0', the charger operates normally.

Register #3

Memory location: 02, Reset state: 1000 1111

(1) Charge voltage range is 3.5V—4.44V with the offset of 3.5V and step of 20mV (default 4.2V)

- **VBATREG –** Sets the battery regulation voltage
- **USB_DET/EN –** Provides status of the D+/D– detection results for spins that include the D+/D– pins or the state of EN1/EN2 for spins that include the EN1/EN2 pins

Register #4

Memory location: 03, Reset state: 0000 0000

(1) Charge current offset is 500 mA and default charge current is 500mA (maximum is 2.0A)

(2) When all bits are 1's, it is external ISET charging mode Termination threshold voltage offset is 50mA. The default termination current is 50mA if the charge is selected from I2C. Otherwise, termination is set to 10% of ICHG in external I_set mode with +/-10% accuracy.

- **I_{CHG}** Sets the charge current regulation
- **I**_{TERM} Sets the current level at which the charger will terminate

Register #5

Memory location: 04, Reset state: xx00 x010

(1) LOOP_STATUS bits show if there are any loop is active that slow down the safety timer. If a status occurs, these bits announce the status and do not clear until read. If more than one occurs, the first one is shown.

- (2) VIN-DPM voltage offset is 4.20V and default V_{IN_DPM} threshold is 4.36V.
- **LOOP STATUS** Provides the status of the active regulation loop. The charge controller allows for only one loop can regulate at a time.
- **LOW_CHG –** When set to a '1', the charge current is reduced 330mA independent of the charge current setting in register 0x03. When set to '0', the charge current is set by register 0x03.
- **DPDM_EN** Forces a D+/D- detection routine to be executed once a '1' is written. This is independent of the input being supplied.
- **CE_STATUS** Provides the status of the \overline{CE} pin level. If the \overline{CE} pin is forced high, this bit returns a '1'. If the \overline{CE} pin is forced low, this bit returns a '0'.
- **VINDPM –** Sets the input VDPM level.

Register #6

Memory location: 05, Reset state: 101x 1xxx

- **2xTMR_EN –** When set to a '1', the 2x Timer function is enabled and allows for the timer to be extended if a condition occurs where the charge current is reduced (i.e. $V_{\text{IN_DPM}}$, thermal regulation, etc.). When set to a '0', this function is disabled and the normal timer will always be executed independent of the current reduce conditions.
- **SYSOFF –** When set to a '1' and the input is removed, the internal battery FET is turned off in order to reduce the leakage from the BAT pin to less than 1µA. Note that this disconnects the battery from the system. When set to a '0', this function is disabled.
- **TS_EN –** Enables and disables the TS function. When set to a '1' the TS function is disabled otherwise it is enabled. Only applies to spins that have a TS pin.
- **TS_STAT –** Provides status of the TS pin state for spins that have a TS pin.

Register #7

Memory location: 06, Reset state: 1110 0000

• **VOVP –** Sets the OVP level

- **CLR_VDP –** When the D+/D– detection has finished, some cases require the D+ pin to force a voltage of 0.6V. This bit allows the system to clear the voltage prior to any communication on the D+/D– pins. A '1' clears the voltage at the $D+$ pin if present.
- **FORCE_BATDET –** Forces battery detection and provides status of the battery presence. A logic '1' enables this function.
- **FORCE_PTM –** Puts the device in production test mode (PTM) where the input current limit is disabled. Note that a battery must not be present prior to using this function. Otherwise the function will not be allowed to execute. A logic '1' enables the PTM function.

APPLICATION INFORMATION

Inductor Selection

The inductor selection depends on the application requirements. The bq2425x is designed to operate at around 1 µH. The value will have an effect on efficiency, and the ripple requirements, stability of the charger, package size, and DCR of the inductor. The 1μH inductor provides a good tradeoff between size and efficiency and ripple.

Once the inductance has been selected, the peak current is needed in order to choose the saturation current rating of the inductor. Make sure that the saturation current is always greater than or equal to the calculated IPEAK. The following equation can be used to calculate the current ripple:

 $\Delta I_1 = \{VBAT (VIN - VBAT)\}/(VIN \times fs \times L)$ (6)

Then use current ripple to calculate the peak current as follows:

 $I_{PEAK} = I_{CHARGE} \times (1 + \Delta I_L/2)$ (7)

In this design example, the regulation voltage is set to 4.2V, the input voltage is 5V and the inductance is selected to be 1μ H. The maximum charge current that can be used in this application is 1A and can be set by I2C command. The peak current is needed in order to choose the saturation current rating of the inductor. Using equation 6 and 7, $Δl_L$ is calculated to be 0.224A and the inductor peak current is 1.112A. A 1μF BAT cap is needed and 22µF SYS cap is needed on the system trace.

The default settings for external fast charge current and external setting of current limit are chosen to be IFC=500mA and ILIM=1A. RISET and RILIM need to be calculated using equation 1 and 2 in the data sheet.

The fast charge current resistor (RISET) can be set as follows:

$$
RISET=250/0.5A=500\Omega
$$

The input current limit resistor (RILIM) can be set as follows:

RILIM= 270/1A=270Ω

The external settings of VIN_DPM can be designed by calculating R1 and R2 according to equation 3 in this data sheet and the typical application circuit. VIN_DPM should be chosen first along with R1. VIN_DPM is chosen to be 4.6V and R1 is set to 274KΩ in this design example. Using equation 3, the value of R2 is calculated to be 100KΩ.

In this design example, the application needs to be JEITA compliant. Thus, T_{COLD} must be 0°C and T_{HOT} must be 60°C. If an NTC resistor is chosen such that the beta is 4500K and the nominal resistance is 13KΩ, the calculated R2 and R3 values are 5KΩ and 8.8KΩ respectively. These results are obtained from equation 4 and 5 in this data sheet.

Layout Guidelines

- 1. Place the BOOT, PMID, IN, BAT, and LDO capacitors as close as possible to the IC for optimal performance.
- 2. Connect the inductor as close as possible to the SW pin, and the SYS/CSIN cap as close as possible to the inductor minimizing noise in the path.
- 3. Place a 1-μF PMID capacitor as close as possible to the PMID and PGND pins, making the high frequency current loop area as small as possible.
- 4. The local bypass capacitor from SYS/CSIN to GND must be connected between the SYS/CSIN pin and PGND of the IC. This minimizes the current path loop area from the SW pin through the LC filter and back to the PGND pin.
- 5. Place all decoupling capacitors close to their respective IC pins and as close as possible to PGND (do not place components such that routing interrupts power-stage currents). All small control signals must be routed away from the high-current paths.
- 6. To reduce noise coupling, use a ground plane if possible, to isolate the noisy traces from spreading its noise all over the board. Put vias inside the PGND pads for the IC.
- 7. The high-current charge paths into IN, Micro-USB, BAT, SYS/CSIN, and from the SW pins must be sized appropriately for the maximum charge current to avoid voltage drops in these traces.
- 8. For high-current applications, the balls for the power paths must be connected to as much copper in the board as possible. This allows better thermal performance because the board conducts heat away from the IC.

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Board Layout

Figure 30. Recommended bq2425x PCB Layout for WCSP Package

0-Pin A1 Marker, TI-TI Letters, YM- Year Month Date Code, LLLL-Lot Trace Code, S-Assembly Site Code

The bq2425x devices are available in a 30-bump chip scale package (YFF, NanoFree™). The package dimensions are:

- $D 2.427$ mm ± 0.035 mm
- E 2.027mm ±0.035mm

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REVISION HISTORY

Changes from Original (October 2012) to Revision A Page

Changes from Revision A (March 2013) to Revision B Page

• Added PREVIEW status to devices in the Ordering Information table, except the bq24250RGER and bq24250RGET [3](#page-2-0)

Changes from Revision B (May 2013) to Revision C Page

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PACKAGING INFORMATION

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

⁽²⁾ Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check<http://www.ti.com/productcontent>for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

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Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes. Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

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PACKAGE MATERIALS INFORMATION

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TAPE AND REEL INFORMATION

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

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PACKAGE MATERIALS INFORMATION

MECHANICAL DATA

NOTES: All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994. А.

- **B.** This drawing is subject to change without notice.
- Quad Flatpack, No-Leads (QFN) package configuration. С.
- The package thermal pad must be soldered to the board for thermal and mechanical performance. D.
- E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.
- F. Falls within JEDEC MO-220.

4206344-4/AD 04/13

PLASTIC QUAD FLATPACK NO-LEAD

RGE (S-PVQFN-N24) THERMAL INFORMATION This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC). For information on the Quad Flatpack No-Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at www.ti.com. The exposed thermal pad dimensions for this package are shown in the following illustration. PIN 1 INDICATOR C 0.30 6 U UU U \perp \Box 24 7 Exposed Thermal Pad 2,70±0,10 ٢ 12 $\overline{19}$ $\overline{18}$ $\overline{13}$ 2,70±0,10 Bottom View Exposed Thermal Pad Dimensions

NOTES: A. All linear dimensions are in millimeters

RGE (S-PVQFN-N24)

PLASTIC QUAD FLATPACK NO-LEAD

NOTES:

- A. All linear dimensions are in millimeters.
	- B. This drawing is subject to change without notice.
	- Publication IPC-7351 is recommended for alternate designs. C.
	- D. This package is designed to be soldered to a thermal pad on the board. Refer to Application Note, Quad Flat-Pack Packages, Texas Instruments Literature No. SLUA271, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <http://www.ti.com>.
	- E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
	- $F_{\rm{eff}}$ Customers should contact their board fabrication site for recommended solder mask tolerances and via tenting recommendations for vias placed in the thermal pad.

YFF (R-XBGA-N30)

DIE-SIZE BALL GRID ARRAY

A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.

- B. This drawing is subject to change without notice.
- C. NanoFree™ package configuration.

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